

ECE4270
Fundamentals of DSP

Lecture 4

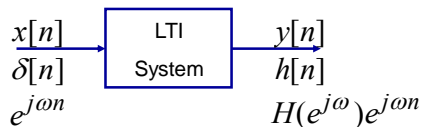
Discrete-Time Fourier Transform

School of ECE
Center for Signal and Information Processing
Georgia Institute of Technology

Overview of Lecture 4

- Examples of Freq. Response (Last Lecture)
- Plotting the frequency response (Last Lecture)
- Response of an LTI system to a cosine signal
- Definition of the discrete-time Fourier transform
- The frequency response as DTFT of the impulse response
- Ideal Lowpass filter
- Examples of DTFT
- Symmetry properties of the DTFT
- Examples of usage of the DTFT

Last Lecture: Complex Exponential Input Signals



Frequency response

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega k}$$

Examples

- Delay: $y[n] = x[n - n_d]$
 $h[n] = \delta[n - n_d] \Rightarrow x[n] * \delta[n - n_d] = x[n - n_d]$

- Moving Average: $y[n] = \frac{1}{M+1} \sum_{k=0}^M x[n - k]$

$$h[n] = \frac{1}{M+1} \sum_{k=0}^M \delta[n - k]$$

- First difference: $y[n] = x[n] - x[n - 1]$

$$h[n] = \delta[n] - \delta[n - 1]$$

Delay and First Difference

• Delay: $y[n] = x[n - n_d]$ $h[n] = \delta[n - n_d]$

$$x[n] = e^{j\omega n} \mapsto y[n] = e^{j\omega(n-n_d)} = \underbrace{e^{-j\omega n_d}}_{H(e^{j\omega})} e^{j\omega n}$$

$$H(e^{j\omega}) = e^{-j\omega n_d}$$

• First difference:

$$y[n] = x[n] - x[n-1] \quad h[n] = \delta[n] - \delta[n-1]$$

$$x[n] = e^{j\omega n} \mapsto y[n] = e^{j\omega n} - e^{j\omega(n-1)} = \underbrace{(1 - e^{-j\omega})}_{H(e^{j\omega})} e^{j\omega n}$$

$$H(e^{j\omega}) = 1 - e^{-j\omega}$$

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Moving Average

$$y[n] = \frac{1}{M+1} \sum_{k=0}^M x[n-k]$$

$$x[n] = e^{j\omega n} \mapsto y[n] = \frac{1}{M+1} \sum_{k=0}^M e^{j\omega(n-k)}$$

$$= \frac{1}{M+1} \underbrace{\sum_{k=0}^M e^{-j\omega k}}_{H(e^{j\omega})} e^{j\omega n}$$

$$H(e^{j\omega}) = \frac{1}{M+1} \sum_{k=0}^M e^{-j\omega k}$$

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Moving Average Frequency Response

$$H(e^{j\omega}) = \frac{1}{M+1} \sum_{k=0}^M e^{-j\omega k} = \frac{1}{M+1} \frac{(1 - e^{-j\omega(M+1)})}{(1 - e^{-j\omega})}$$

$$H(e^{j\omega}) = \frac{1}{M+1} \frac{(e^{j\omega(M+1)/2} - e^{-j\omega(M+1)/2})e^{-j\omega(M+1)/2}}{(e^{j\omega/2} - e^{-j\omega/2})e^{-j\omega/2}}$$

$$H(e^{j\omega}) = \frac{1}{M+1} \frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$$

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Plotting using MATLAB

»help freqz

FREQZ Z-transform digital filter frequency response.

When N is an integer, [H,W] = FREQZ(B,A,N) returns the N-point frequency vector W in radians and the N-point complex frequency response vector H given numerator and denominator coefficients in vectors B and A. The frequency response is evaluated at N points equally spaced around the upper half of the unit circle. If N isn't specified, it defaults to 512.

```
>> omega=(0:400)*pi/400; b=[1,1,1,1,1]/5;
```

```
>> H=freqz(b,1,omega);
```

```
>> subplot(211); plot(omega/pi,abs(H))
```

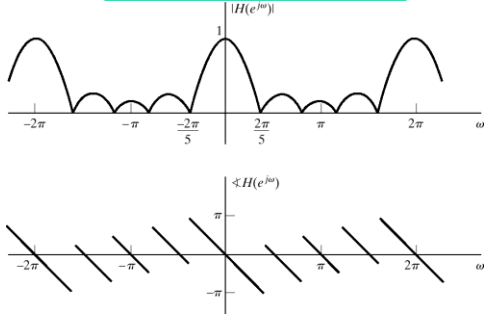
```
>> subplot(212); plot(omega/pi,angle(H))
```

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Plotting the Frequency Response

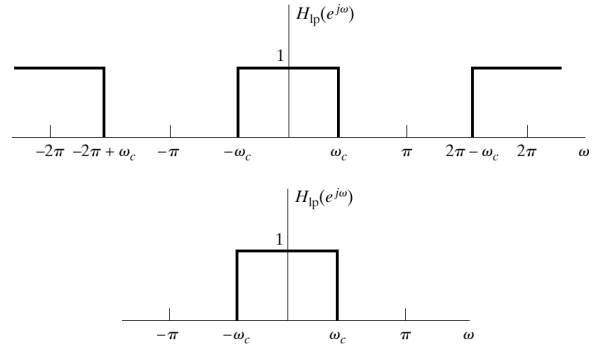
$$H(e^{j\omega}) = \frac{1 \sin[\omega 5 / 2]}{5 \sin(\omega / 2)} e^{-j\omega 2} \quad M=4$$



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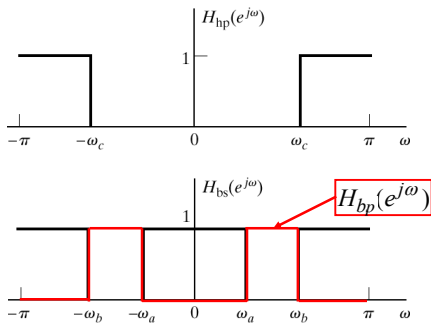
Ideal Lowpass Filter



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Frequency Selective Filters



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Suddenly Applied Complex Exponential to a Causal System

$$x[n] = e^{j\omega n} u[n] \mapsto y[n] = \begin{cases} 0 & n < 0 \\ \left(\sum_{k=0}^n h[k] e^{-j\omega k} \right) e^{j\omega n} & n \geq 0 \end{cases}$$

$$y[n] = \left(\sum_{k=0}^{\infty} h[k] e^{-j\omega k} \right) e^{j\omega n} - \left(\sum_{k=n+1}^{\infty} h[k] e^{-j\omega k} \right) e^{j\omega n}$$

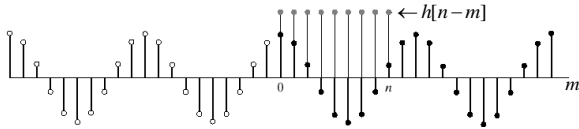
$$y[n] = H(e^{j\omega}) e^{j\omega n} - \left(\sum_{m=-1}^{-\infty} h[n-m] e^{-j\omega(n-m)} \right) e^{j\omega n}$$

$$y[n] = H(e^{j\omega}) e^{j\omega n} - \left(\sum_{m=-\infty}^{-1} h[n-m] e^{j\omega m} \right)$$

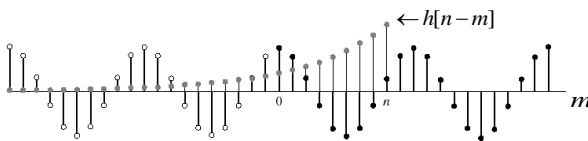
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Sinusoidal Steady State



$$y[n] = H(e^{j\omega})e^{j\omega n} - \left(\sum_{m=-\infty}^{-1} h[n-m]e^{j\omega m} \right)$$



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Response to a Cosine

$$x[n] = A \cos(\omega_0 n + \phi) = \frac{A}{2} e^{j\phi} e^{j\omega_0 n} + \frac{A}{2} e^{-j\phi} e^{-j\omega_0 n}$$

$$y[n] = H(e^{j\omega_0}) \frac{A}{2} e^{j\phi} e^{j\omega_0 n} + H(e^{-j\omega_0}) \frac{A}{2} e^{-j\phi} e^{-j\omega_0 n}$$

$$y[n] = |H(e^{j\omega_0})| e^{j\angle H(e^{j\omega_0})} \frac{A}{2} e^{j\phi} e^{j\omega_0 n} + |H(e^{-j\omega_0})| e^{j\angle H(e^{-j\omega_0})} \frac{A}{2} e^{-j\phi} e^{-j\omega_0 n}$$

$$y[n] = |H(e^{j\omega_0})| A \cos[\omega_0 n + \phi + \angle H(e^{j\omega_0})]$$

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Discrete-Time Fourier Transform

- Definition:

$$X(e^{j\omega}) = \sum_{n=-\infty}^{\infty} x[n] e^{-j\omega n} \quad \text{Direct Transform}$$

$$x[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega \quad \text{Inverse Transform}$$

- Existence of the DTFT:

$$|X(e^{j\omega})| \leq \sum_{n=-\infty}^{\infty} |x[n]| e^{-j\omega n} \leq \sum_{n=-\infty}^{\infty} |x[n]| < \infty$$

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Frequency Response Again

- The frequency response function is now seen to be just the DTFT of the impulse response.

$$H(e^{j\omega}) = \sum_{k=-\infty}^{\infty} h[k] e^{-j\omega k}$$

- Note that stable systems have frequency responses.

$$\sum_{n=-\infty}^{\infty} |h[n]| < \infty$$

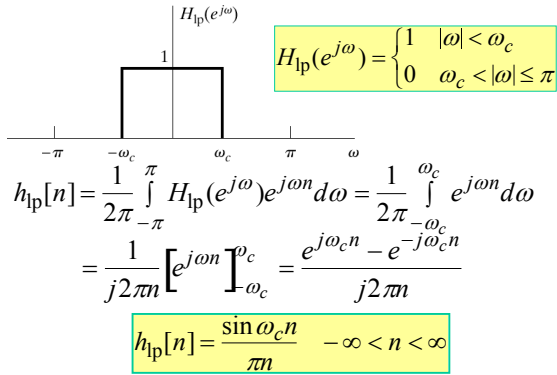
- Therefore, the impulse response is just the inverse DTFT of the frequency response.

$$h[n] = \frac{1}{2\pi} \int_{-\pi}^{\pi} H(e^{j\omega}) e^{j\omega n} d\omega$$

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Ideal Lowpass Filter



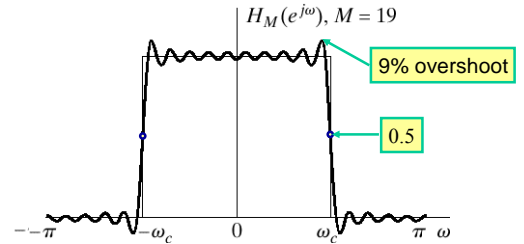
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Convergence

- It should be true that

$$\lim_{M \rightarrow \infty} \left(\sum_{n=-M}^M \frac{\sin \omega_c n}{\pi n} e^{-j\omega n} \right) \rightarrow \begin{cases} 1 & |\omega| < \omega_c \\ 0 & \omega_c < |\omega| \leq \pi \end{cases}$$



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Example of DTFT

- Consider a signal $x[n] = Ar^n \cos(\omega_0 n + \phi)u[n]$
- To find its DTFT, break it up into complex exponentials

$$x[n] = \frac{A}{2} e^{j\phi} r^n e^{j\omega_0 n} u[n] + \frac{A}{2} e^{-j\phi} r^n e^{-j\omega_0 n} u[n]$$

- Therefore, the DTFT is

$$X(e^{j\omega}) = \frac{\frac{A}{2} e^{j\phi}}{1 - r e^{j\omega_0} e^{-j\omega}} + \frac{\frac{A}{2} e^{-j\phi}}{1 - r e^{-j\omega_0} e^{-j\omega}}$$

$X(e^{j\omega}) = \frac{A \cos \phi - Ar \cos(\omega_0 - \phi) e^{-j\omega}}{1 - 2r \cos \omega_0 e^{-j\omega} + r^2 e^{-j2\omega}}$

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More Example of DTFT

- Consider the real exponential signal

$x[n] = a^n u[n]$

- Its DTFT is obtained as follows:

$$X(e^{j\omega}) = \sum_{n=0}^{\infty} a^n e^{-j\omega n} = \sum_{n=0}^{\infty} (ae^{-j\omega})^n = \frac{1}{1 - ae^{-j\omega}}$$

$$X(e^{j\omega}) = \frac{1 - ae^{j\omega}}{(1 - ae^{-j\omega})(1 - ae^{j\omega})}$$

$$= \frac{1 - a \cos \omega}{\underbrace{1 + a^2 - 2a \cos \omega}_{X_R(e^{j\omega})}} + j \frac{-a \sin \omega}{\underbrace{1 + a^2 - 2a \cos \omega}_{X_I(e^{j\omega})}}$$

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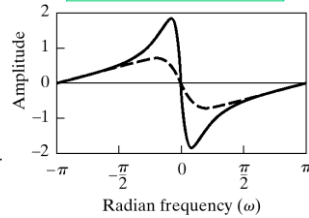
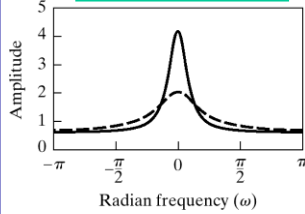
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Real and Imaginary Parts

$$X(e^{j\omega}) = \underbrace{\frac{1 - a \cos \omega}{1 + a^2 - 2a \cos \omega}}_{X_R(e^{j\omega})} + j \underbrace{\frac{-a \sin \omega}{1 + a^2 - 2a \cos \omega}}_{X_I(e^{j\omega})}$$

$$X_R(e^{j\omega}) = X_R(e^{-j\omega})$$

$$X_I(e^{j\omega}) = -X_I(e^{-j\omega})$$



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Magnitude and Angle Form

$$x[n] = a^n u[n] \Leftrightarrow X(e^{j\omega}) = \frac{1}{1 - ae^{-j\omega}}$$

$$X(e^{j\omega}) = |X(e^{j\omega})| e^{j\angle X(e^{j\omega})}$$

$$\begin{aligned} |X(e^{j\omega})|^2 &= X(e^{j\omega}) X^*(e^{j\omega}) = \frac{1}{(1 - ae^{-j\omega})(1 - ae^{j\omega})} \\ &= \frac{1}{1 + a^2 - 2a \cos \omega} \end{aligned}$$

$$\angle X(e^{j\omega}) = \arctan\left(\frac{-a \sin \omega}{1 - a \cos \omega}\right)$$

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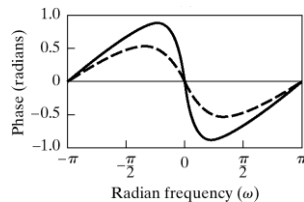
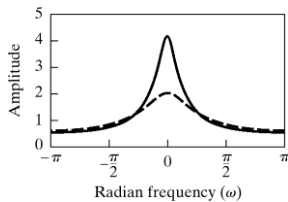
Magnitude and Angle Plots

$$|X(e^{j\omega})| = \frac{1}{(1 + a^2 - 2a \cos \omega)^{1/2}}$$

$$\angle X(e^{j\omega}) = \arctan\left(\frac{-a \sin \omega}{1 - a \cos \omega}\right)$$

$$|X(e^{j\omega})| = |X(e^{-j\omega})|$$

$$\angle X(e^{j\omega}) = -\angle X(e^{-j\omega})$$



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TABLE 2.1 SYMMETRY PROPERTIES OF THE FOURIER TRANSFORM

Sequence $x[n]$	Fourier Transform $X(e^{j\omega})$
1. $x^*[n]$	$X^*(e^{-j\omega})$
2. $x^*[-n]$	$X^*(e^{j\omega})$
3. $\Re\{x[n]\}$	$X_e(e^{j\omega})$ (conjugate-symmetric part of $X(e^{j\omega})$)
4. $j\Im\{x[n]\}$	$X_o(e^{j\omega})$ (conjugate-antisymmetric part of $X(e^{j\omega})$)
5. $x_e[n]$ (conjugate-symmetric part of $x[n]$)	$X_R(e^{j\omega}) = \Re\{X(e^{j\omega})\}$
6. $x_o[n]$ (conjugate-antisymmetric part of $x[n]$)	$jX_I(e^{j\omega}) = j\Im\{X(e^{j\omega})\}$
<i>The following properties apply only when $x[n]$ is real:</i>	
7. Any real $x[n]$	$X(e^{j\omega}) = X^*(e^{-j\omega})$ (Fourier transform is conjugate symmetric)
8. Any real $x[n]$	$X_R(e^{j\omega}) = X_R(e^{-j\omega})$ (real part is even)
9. Any real $x[n]$	$X_I(e^{j\omega}) = -X_I(e^{-j\omega})$ (imaginary part is odd)
10. Any real $x[n]$	$ X(e^{j\omega}) = X(e^{-j\omega}) $ (magnitude is even)
11. Any real $x[n]$	$\angle X(e^{j\omega}) = -\angle X(e^{-j\omega})$ (phase is odd)
12. $x_e[n]$ (even part of $x[n]$)	$X_R(e^{j\omega})$
13. $x_o[n]$ (odd part of $x[n]$)	$jX_I(e^{j\omega})$

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Frequency Response of a DE

$$\sum_{k=0}^N a_k y[n-k] = \sum_{k=0}^M b_k x[n-k]$$

$$\sum_{k=0}^N a_k Y(e^{j\omega}) e^{-j\omega k} = \sum_{k=0}^M b_k X(e^{j\omega}) e^{-j\omega k}$$

$$\left(\sum_{k=0}^N a_k e^{-j\omega k} \right) Y(e^{j\omega}) = \left(\sum_{k=0}^M b_k e^{-j\omega k} \right) X(e^{j\omega})$$

$$H(e^{j\omega}) = \frac{Y(e^{j\omega})}{X(e^{j\omega})} = \frac{\left(\sum_{k=0}^M b_k e^{-j\omega k} \right)}{\left(\sum_{k=0}^N a_k e^{-j\omega k} \right)}$$

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Using the DTFT

- The DTFT provides a “frequency-domain” representation that is invaluable for thinking about and solving DSP problems.
- To use it effectively you must
 - know the Fourier transforms of certain important signals
 - know its properties and certain key theorems
 - be able to combine time-domain and frequency domain methods appropriately

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TABLE 2.3 FOURIER TRANSFORM PAIRS

Sequence	Fourier Transform
1. $\delta[n]$	1
2. $\delta[n - n_0]$	$e^{-j\omega n_0}$
3. 1 ($-\infty < n < \infty$)	$\sum_{k=-\infty}^{\infty} 2\pi \delta(\omega + 2\pi k)$
4. $a^n u[n]$ ($ a < 1$)	$\frac{1}{1 - ae^{-j\omega}}$
5. $u[n]$	$\frac{1}{1 - e^{-j\omega}} + \sum_{k=-\infty}^{\infty} \pi \delta(\omega + 2\pi k)$
6. $(n+1)a^n u[n]$ ($ a < 1$)	$\frac{1}{(1 - ae^{-j\omega})^2}$
7. $\frac{r^n \sin \omega_p (n+1)}{\sin \omega_p} u[n]$ ($ r < 1$)	$\frac{1}{1 - 2r \cos \omega_p e^{-j\omega} + r^2 e^{-j2\omega}}$
8. $\frac{\sin \omega_c n}{\pi n}$	$X(e^{j\omega}) = \begin{cases} 1, & \omega < \omega_c \\ 0, & \omega_c < \omega \leq \pi \end{cases}$
9. $x[n] = \begin{cases} 1, & 0 \leq n \leq M \\ 0, & \text{otherwise} \end{cases}$	$\frac{\sin[\omega(M+1)/2]}{\sin(\omega/2)} e^{-j\omega M/2}$

We worked this one out.

And this one too.

The Unit Impulse Function

- The continuous-variable impulse is defined by the following properties:

$\delta(\omega) = 0$ for $\omega \neq 0$ highly concentrated

$\int_{-\varepsilon}^{\varepsilon} \delta(\omega) d\omega = 1$ for $\varepsilon > 0$ area concentrated

$X(e^{j\omega}) \delta(\omega) = X(e^{j0}) \delta(\omega)$ sampling property

$\delta(\omega) * X(e^{j\omega}) = X(e^{j\omega})$ replicating property

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DTFT of a Constant Signal

- Assume a “periodic impulse train” for the DTFT

$$x[n] = 1 \Leftrightarrow X(e^{j\omega}) = \sum_{r=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi r)$$

- Find the corresponding sequence $x[n]$

$$\begin{aligned} x[n] &= \frac{1}{2\pi} \int_{-\pi}^{\pi} X(e^{j\omega}) e^{j\omega n} d\omega \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \sum_{r=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi r) e^{j\omega n} d\omega \\ &= \frac{1}{2\pi} \int_{-\pi}^{\pi} \cancel{2\pi}\delta(\omega) e^{j\omega n} d\omega = \int_{-\pi}^{\pi} \delta(\omega) e^{j0n} d\omega = 1 \end{aligned}$$

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Very Useful DTFT Pairs

$$x[n] = \delta[n - n_d] \Leftrightarrow X(e^{j\omega}) = e^{-j\omega n_d}$$

$$x[n] = a^n u[n] \Leftrightarrow X(e^{j\omega}) = \frac{1}{1 - ae^{-j\omega}}$$

$$x[n] = 1 \Leftrightarrow X(e^{j\omega}) = \sum_{r=-\infty}^{\infty} 2\pi\delta(\omega + 2\pi r)$$

$$x[n] = \frac{\sin \omega_c n}{\pi n} \Leftrightarrow X(e^{j\omega}) = \begin{cases} 1 & |\omega| < \omega_c \\ 0 & |\omega| > \omega_c \end{cases}$$

$$x[n] = \begin{cases} 1 & 0 \leq n \leq M \\ 0 & \text{otherwise} \end{cases} \Leftrightarrow X(e^{j\omega}) = \frac{\sin[(M+1)\omega/2]}{\sin(\omega/2)} e^{-j\omega M}$$

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