

**Fundamentals of DSP
Lecture 21**

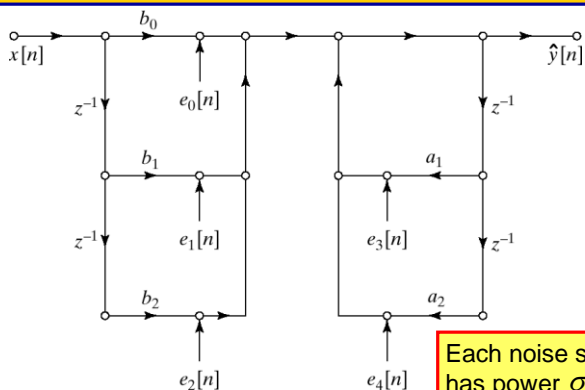
**Round off noise in IIR Filters
and
Ch7: IIR and FIR Filter Design**

School of ECE
Center for Signal and Information Processing
Georgia Institute of Technology

Overview of Lecture

- Roundoff noise in IIR implementations
- Example of noise analysis
- Chapter 7.
 - The filter design problem
 - FIR vs IIR filters
 - Setting up the digital filter design problem.
 - Bilinear Transform

Linear Noise Model



Each noise source has power $\sigma_e^2 = 2^{-2B}/12$

The noise sources are independent so their powers add.

Linear System with a White Noise Input

$$\begin{array}{ccc}
 x[n] & \xrightarrow{\text{LTI System } h[n], H(e^{j\omega})} & y[n] \\
 \phi_{xx}[m] = \sigma_x^2 \delta[m] & & \phi_{yy}[m] = \sigma_x^2 c_{hh}[m] \\
 \Phi_{xx}(e^{j\omega}) = \sigma_x^2 & & \Phi_{yy}(e^{j\omega}) = \sigma_x^2 C_{hh}(e^{j\omega})
 \end{array}$$

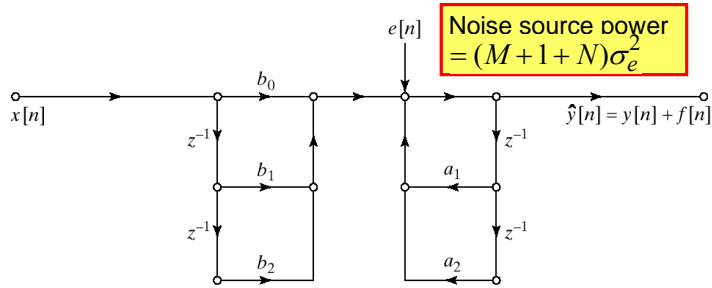
$$\phi_{yy}[m] = \phi_{xx}[m] * c_{hh}[m] = \sigma_x^2 \delta[m] * c_{hh}[m] = \sigma_x^2 c_{hh}[m]$$

$$c_{hh}[m] = \sum_{k=-\infty}^{\infty} h[m+k]h^*[k] = h[-m] * h^*[m]$$

$$\Phi_{yy}(e^{j\omega}) = \Phi_{xx}(e^{j\omega})C_{hh}(e^{j\omega}) = \sigma_x^2 C_{hh}(e^{j\omega})$$

$$C_{hh}(e^{j\omega}) = H(e^{-j\omega})H^*(e^{-j\omega}) = |H(e^{-j\omega})|^2$$

Combined Noise Sources



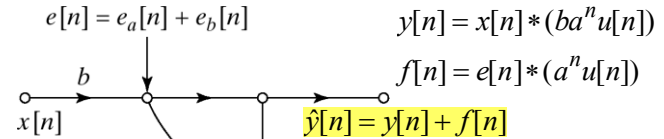
Noise source power
 $= (M + 1 + N)\sigma_e^2$

$$\Phi_{ff}(e^{j\omega}) = \frac{(M + 1 + N)\sigma_e^2}{|A(e^{j\omega})|^2}$$

ECE4270

Spring 2017

Example (Output Noise Power)



$$e[n] = e_a[n] + e_b[n] \quad y[n] = x[n] * (ba^n u[n])$$

$$f[n] = e[n] * (a^n u[n])$$

$$\hat{y}[n] = y[n] + f[n]$$

$$\Phi_{ff}(e^{j\omega}) = \frac{2\sigma_e^2}{|A(e^{j\omega})|^2} = \frac{2\sigma_e^2}{1 + a^2 - 2a \cos \omega}$$

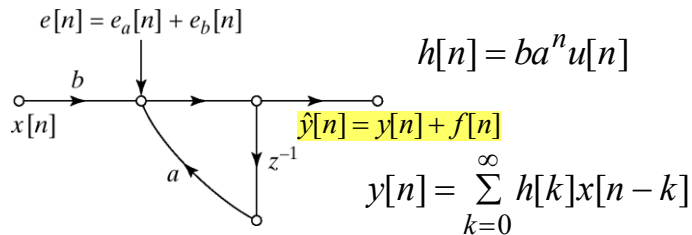
$$\sigma_f^2 = 2\sigma_e^2 \sum_{n=0}^{\infty} |h_{ef}[n]|^2 = 2\sigma_e^2 \sum_{n=0}^{\infty} a^{2n} = \frac{2\sigma_e^2}{1 - a^2}$$

$$\lim_{|a| \rightarrow 1} \sigma_f^2 \rightarrow \infty$$

ECE4270

Spring 2017

Example (Avoiding Overflow)



$$e[n] = e_a[n] + e_b[n]$$

$$h[n] = ba^n u[n]$$

$$\hat{y}[n] = y[n] + f[n]$$

$$y[n] = \sum_{k=0}^{\infty} h[k]x[n-k]$$

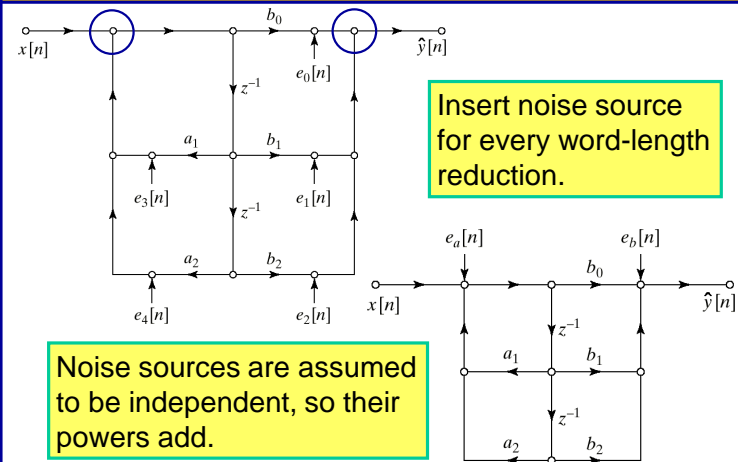
$$sx_{\max} \sum_{k=0}^{\infty} |h[k]| = sx_{\max} |b| \sum_{n=0}^{\infty} |a|^n = sx_{\max} \frac{|b|}{1 - |a|} < 1$$

$$sx_{\max} < \frac{1 - |a|}{|b|} \rightarrow 0 \quad \text{as } |a| \rightarrow 1 \quad \text{SNR decreases as pole moves closer to unit circle.}$$

ECE4270

Spring 2017

Direct Form II Noise Modeling



Insert noise source
 for every word-length
 reduction.

Noise sources are assumed
 to be independent, so their
 powers add.

ECE4270

Spring 2017

IIR Quantization Example

- Consider a 6th-order elliptic filter meeting the specifications

$$0.99 \leq |H(e^{j\omega})| \leq 1.01 \quad 0 \leq \omega \leq 0.5\pi$$

$$|H(e^{j\omega})| \leq 0.01 \quad 0.56\pi \leq \omega \leq \pi$$

$$H(z) = 0.079459 \prod_{k=1}^3 H_k(z)$$

$$= 0.079459 \prod_{k=1}^3 \left(\frac{1 + b_{1k}z^{-1} + z^{-2}}{1 - a_{1k}z^{-1} - a_{2k}z^{-2}} \right)$$

TABLE 6.4 COEFFICIENTS FOR ELLIPTIC LOWPASS FILTER IN CASCADE FORM

k	a _{1k}	a _{2k}	b _{1k}
1	0.478882	-0.172150	1.719454
2	0.137787	-0.610077	0.781109
3	-0.054779	-0.902374	0.411452

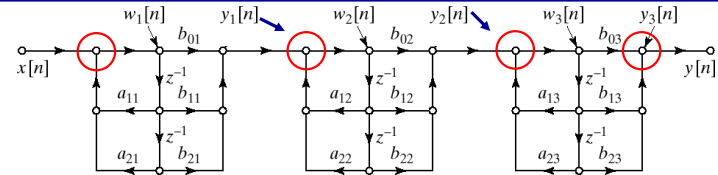
$$H(z) = \prod_{k=1}^3 \left(\frac{b'_{0k} + b'_{1k}z^{-1} + b'_{2k}z^{-2}}{1 - a_{1k}z^{-1} - a_{2k}z^{-2}} \right)$$

$$b'_{01}b'_{02}b'_{03} = 0.079459$$

ECE4270

Spring 2017

Absolute Scaling an IIR Digital Filter



Form II

$$y_i[n] = \sum_{k=0}^{\infty} h_i[k]x[n-k]$$

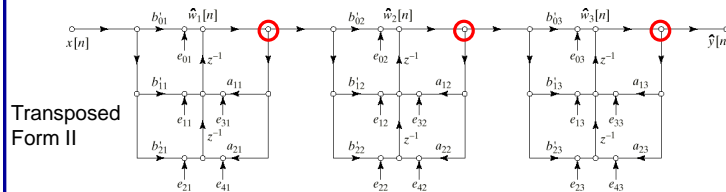
$$|y_i[n]| \leq \max\{x[n]\} \sum_{k=0}^{\infty} |h_i[k]| < 1 \Rightarrow \text{no overflow??}$$

Problem: **Overflow can occur at any summing node.**

ECE4270

Spring 2017

Cascade Implementation (I)



Avoiding overflow:

$$H(z) = \{s_1 H_1(z)\} \{s_2 H_2(z)\} \{s_3 H_3(z)\} \quad \text{where } s_1 s_2 s_3 = 0.079459$$

$$s_1 \max |H_1(e^{j\omega})| \leq 1 \quad s_1 s_2 \max |H_1(e^{j\omega}) H_2(e^{j\omega})| \leq 1$$

$$b'_{k1} = 0.186447 b_{k1} \quad b'_{k2} = 0.529236 b_{k2} \quad b'_{k3} = 0.805267 b_{k3}$$

ECE4270

Spring 2017

Conclusions

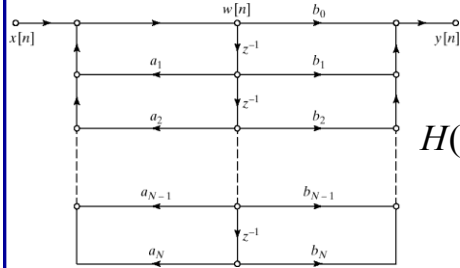
- Coefficient quantization can modify the pole/zero locations and therefore the frequency response.
 - This is very severe for direct form structures
 - Quantization of coefficients may cause instability
- There is a strong interaction between roundoff noise and scaling in IIR filters
 - Roundoff noise has fixed size. Must keep signal values large, but avoid overflow.
 - This is more complicated for IIR than for FIR

ECE4270

Spring 2017

IIR Filter Design

- Find $B(z)$ and $A(z)$ so that the filter meets the specifications on the frequency response.



$$H(e^{j\omega}) = H(z)|_{z=e^{j\omega}}$$

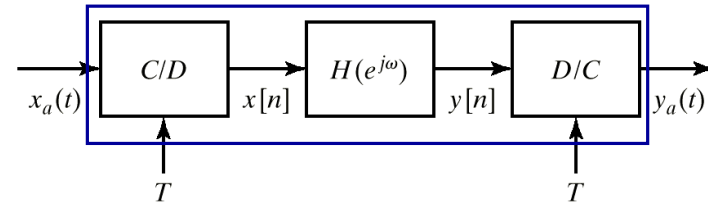
$$H(z) = \frac{\sum_{k=0}^M b_k z^{-k}}{1 - \sum_{k=1}^N a_k z^{-k}} = \frac{B(z)}{A(z)}$$

Rational function approximation

ECE4270

Spring 2017

Digital Filtering



$$H_{\text{eff}}(j\Omega) = \begin{cases} H(e^{j\Omega T}), & |\Omega| < \pi / T \\ 0, & |\Omega| > \pi / T \end{cases}$$

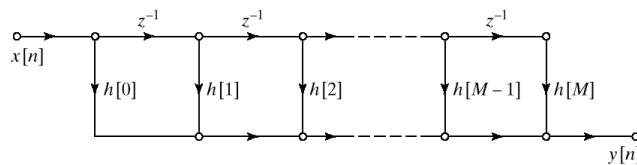
$$H(e^{j\omega}) = H_{\text{eff}}\left(j\frac{\omega}{T}\right), \quad |\omega| < \pi$$

ECE4270

Spring 2017

FIR Filter Design

- Find the impulse response so that the filter meets a set of specifications on the frequency response.



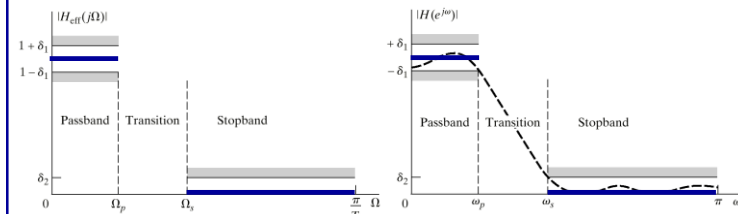
$$H(z) = \sum_{n=0}^M h[n] z^{-n} \quad H(e^{j\omega}) = H(z)|_{z=e^{j\omega}}$$

Polynomial approximation

ECE4270

Spring 2017

Setting the Specifications



$$H_{\text{eff}}(j\Omega) = \begin{cases} H(e^{j\Omega T}), & |\Omega| < \pi / T \\ 0, & |\Omega| > \pi / T \end{cases}$$

$$H(e^{j\omega}) = H_{\text{eff}}\left(j\frac{\omega}{T}\right), \quad |\omega| < \pi$$

ECE4270

Spring 2017

A Design Example

- The C-T specifications are ($1/T=2000$ Hz):

$$0.99 \leq |H_{\text{eff}}(j\Omega)| \leq 1.01, \quad |\Omega| \leq 2\pi(400)$$

$$|H_{\text{eff}}(j\Omega)| \leq 0.001, \quad 2\pi(600) \leq |\Omega| \leq 2\pi(1000)$$
 i.e., $\Omega_p = 2\pi(400)$ and $\Omega_s = 2\pi(600)$.
- The corresponding D-T specifications are:

$$0.99 \leq |H(e^{j\omega})| \leq 1.01, \quad |\omega| \leq 0.4\pi$$

$$|H(e^{j\omega})| \leq 0.001, \quad 0.6\pi \leq |\omega| \leq \pi$$
 i.e., $\omega_p = \Omega_p T = 0.4\pi$ and $\omega_s = \Omega_s T = 0.6\pi$.

ECE4270

Spring 2017

Bilinear Transformation

- We simply transform an analog filter $H_c(s)$ into a digital filter $H(z)$ with the complex mapping

$$s = \frac{2}{T_d} \left(\frac{1-z^{-1}}{1+z^{-1}} \right); \text{ i.e., } H(z) = H_c(s) \Big|_{s=\frac{2}{T_d} \left(\frac{1-z^{-1}}{1+z^{-1}} \right)}$$

$$z = \left(\frac{1+sT_d/2}{1-sT_d/2} \right) \Rightarrow re^{j\omega} = \left(\frac{1+\sigma T_d/2 + j\Omega T_d/2}{1-\sigma T_d/2 - j\Omega T_d/2} \right)$$

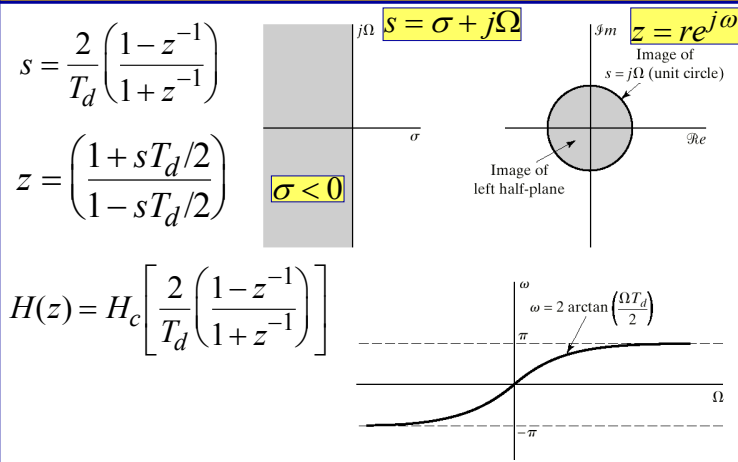
$$\sigma = 0 \Rightarrow r = 1 \text{ and } \frac{\omega}{2} = \arctan(\Omega T_d/2)$$

$$\sigma < 0 \Rightarrow r < 1 \text{ and } \sigma > 0 \Rightarrow r > 1$$

ECE4270

Spring 2017

Bilinear Transformation



ECE4270

Spring 2017

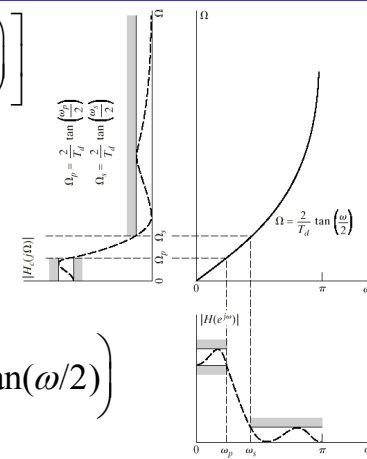
Bilinear Transformation of $H_c(j\Omega)$

$$H(z) = H_c \left[\frac{2}{T_d} \left(\frac{1-z^{-1}}{1+z^{-1}} \right) \right]$$

$$\frac{\omega}{2} = \arctan(\Omega T_d/2)$$

$$\Omega = \frac{2}{T_d} \tan(\omega/2)$$

$$H(e^{j\omega}) = H_c \left(j \frac{2}{T_d} \tan(\omega/2) \right)$$



ECE4270

Spring 2017